

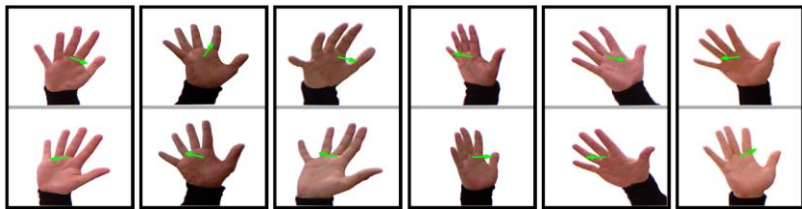
Motivation

Learning the mapping of 2D images onto 3D orientations defined by two hand orientation angles

Ambiguity in hand orientation regression dataset results in:

- Symmetry problem:

opposite orientation \leftrightarrow similar hand shapes



- Existing regression methods *try to fit* into the data
- Overcome using probabilistic regression

PROPEL

$$L = -\log \left[\frac{2 \int P_{gt} P_m d\mathbf{x}}{\int (P_{gt}^2 + P_m^2) d\mathbf{x}} \right]$$

$$P_{gt}^k = \frac{e^{-\frac{1}{2} \left[\frac{(x_1 - \mu_{x_{1k}})^2}{\sigma_{x_{1k}}} + \dots + \frac{(x_n - \mu_{x_{nk}})^2}{\sigma_{x_{nk}}} \right]}}{(\sqrt{2\pi})^n \sqrt{\sigma_{x_{1k}} \dots \sigma_{x_{nk}}}}$$

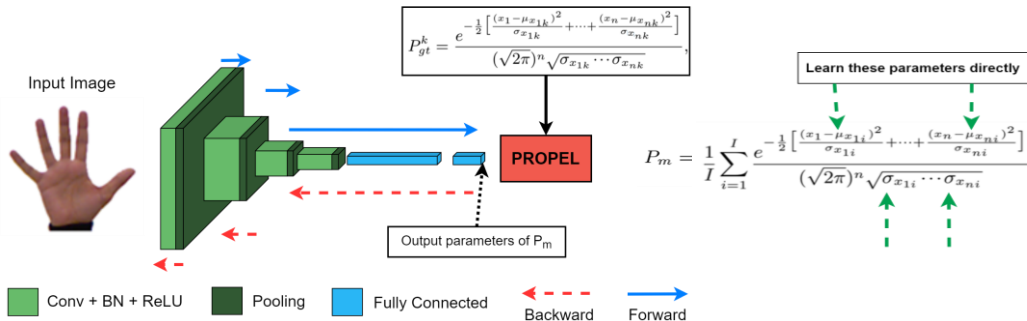
Ground Truth Distribution

$$P_m = \frac{1}{I} \sum_{i=1}^I e^{-\frac{1}{2} \left[\frac{(x_1 - \mu_{x_{1i}})^2}{\sigma_{x_{1i}}} + \dots + \frac{(x_n - \mu_{x_{ni}})^2}{\sigma_{x_{ni}}} \right]}}{(\sqrt{2\pi})^n \sqrt{\sigma_{x_{1i}} \dots \sigma_{x_{ni}}}}$$

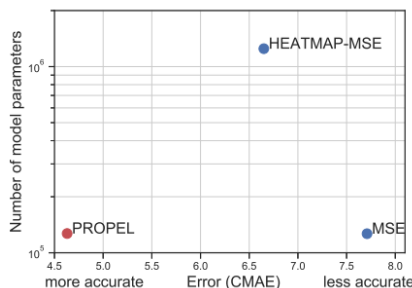
Model Output Distribution

Contributions

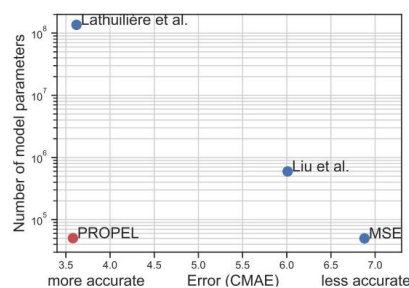
- Enable CNNs to learn parameters of a mixture of Gaussians probability distribution
- Fully-differentiable \rightarrow analytic closed form solution \rightarrow works with standard optimizers
- Generalizable to \rightarrow higher dimensional targets \rightarrow multi-modal distributions
- Better generalization with **10x less model parameters**



Results



Hand Orientation Estimation



Head Orientation Estimation

